

# Efficient learning in graphs and in combinatorial multi-armed bandits

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Ruo-Chun Tzeng

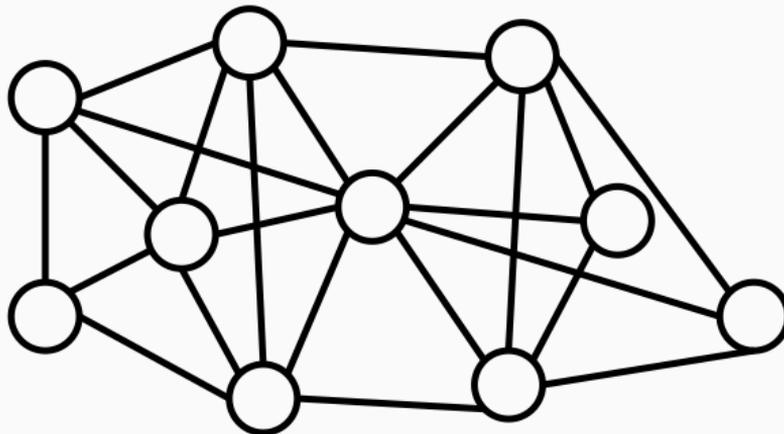
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- [TOG20] "Discovering conflicting groups in signed networks." In Proc. of NeurIPS 2020.
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- [TOA24] "Matroid Semi-bandits in Sublinear Time." In Proc. of ICML 2024.

# Introduction

Given a graph  $G = (V, E)$  with  $w : E \rightarrow \mathbb{R}$ ,



we'd like to solve a combinatorial optimization problem:

$$\max_{x \in \mathcal{X}} f_w(x)$$

for some function  $f_w$  and some combinatorial set  $\mathcal{X}$ .

# Part I - Graph mining

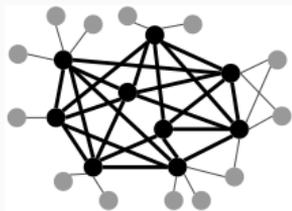
- the edge weight  $w$  is **known**
- $f_w(\mathbf{x})$  quantifies how much the solution  $\mathbf{x}$  matches a specific pattern that we are searching for

We focus on graph mining tasks of the following form:

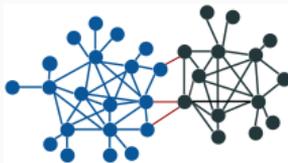
$$\max_{\mathbf{x} \in \mathcal{X}} \frac{\mathbf{x}^T \mathbf{A} \mathbf{x}}{\mathbf{x}^T \mathbf{x}}.$$

Examples include:

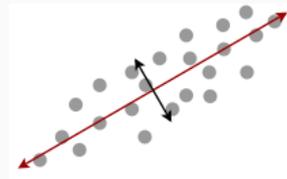
densest subgraph detection



2-community detection



PCA



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We focus on graph mining tasks of the following form:

$$\max_{\mathbf{x} \in \mathcal{X}} \frac{\mathbf{x}^T \mathbf{A} \mathbf{x}}{\mathbf{x}^T \mathbf{x}}.$$

Included papers:

- "Discovering conflicting groups in signed networks." In Proc. of NeurIPS 2020.
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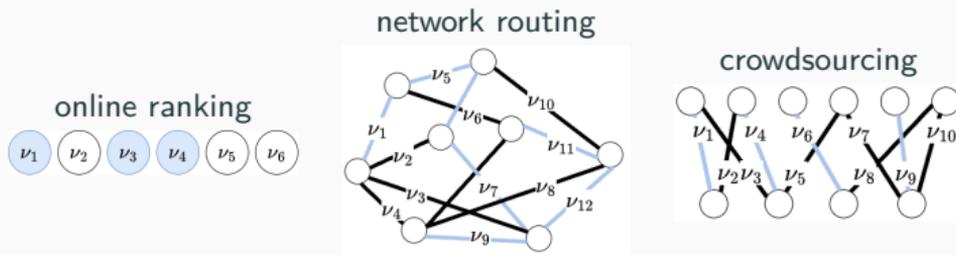
## Part II - Combinatorial multi-armed bandits

- the edge weight  $w$  is **unknown** and observed through stochastic samples
- $f_w(\mathbf{x})$  is the reward function whose dependency on  $w$  is known

We focus on stochastic semi-bandit with linear reward

$$f_w(\mathbf{x}) = \sum_{k \in \text{supp}(\mathbf{x})} w(k)$$

Applications include:



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## **Part I - Graph mining: explicit structure mining**

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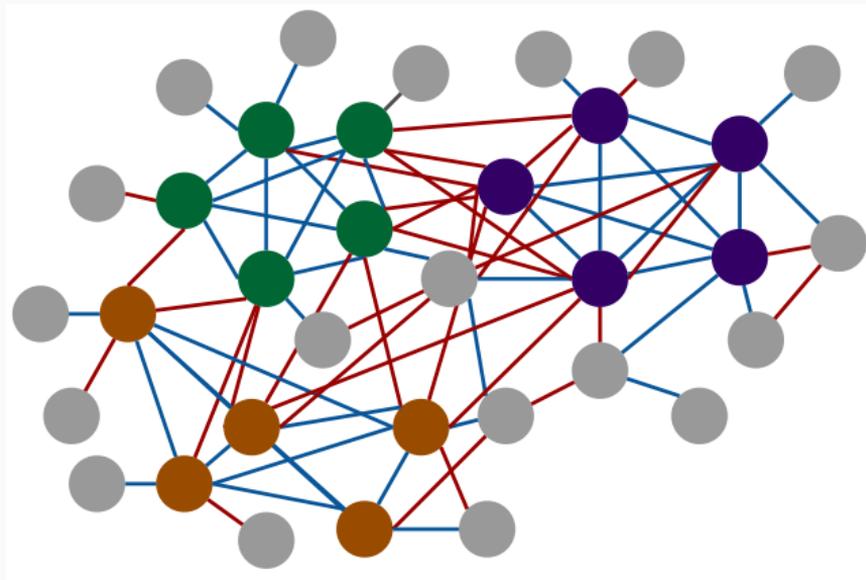
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- We show each conflicting groups is characterized by a maximum discrete Rayleigh's quotient (**MAX-DRQ**) problem
- We present an eigenvector-based algorithm with provable guarantee to the **MAX-DRQ** problem

## [TOG20] Problem: $k$ -conflicting groups detection

Given a signed graph, the goal is to find  $k$  disjoint groups  $S_1, \dots, S_k \subseteq V$  with mostly + intra-group edges and mostly - inter-group edges



- It has been studied by [BCMV12, BGG<sup>+</sup>19]

$$\max_{\substack{S_1, S_2 \subseteq V \\ S_1 \cap S_2 = \emptyset}} \frac{\sum_{h=1,2} \sum_{(i,j) \in E(S_h)} A_{i,j} + \sum_{(i,j) \in E(S_1, S_2)} (-A_{i,j})}{|S_1 \cup S_2|} = \max_{\mathbf{x} \in \{0, \pm 1\}^n \setminus \{0_n\}} \frac{\mathbf{x}^T \mathbf{A} \mathbf{x}}{\mathbf{x}^T \mathbf{x}},$$

where  $\mathbf{A} \in \{0, \pm 1\}^{n \times n}$  is the signed adjacency matrix

- $A_{i,j} x_i x_j = 1$ : + intra-group edges and - inter-group edges
- $A_{i,j} x_i x_j = -1$ : - intra-group edges and + inter-group edges

- It has been studied by [BCMV12, BGG<sup>+</sup>19]

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- [BCMV12, BGG<sup>+</sup>19] showed the problem is APX-hard
- $\mathcal{O}(\sqrt{n})$ -approx eigenvector-based algorithm by [BGG<sup>+</sup>19]
- $\tilde{\mathcal{O}}(n^{\frac{1}{3}})$ -approx SDP-based algorithm by [BCMV12]

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  - $\tilde{\mathcal{O}}(n^{\frac{1}{3}})$ -approx SDP-based algorithm by [BCMV12]
- ( $k \geq 2$ ) **Our contribution:** generalize the (i) problem formulation and (ii) algorithmic framework to the case  $k \geq 2$

- We propose the following problem formulation of  $k$ -conflicting group detection:

$$\max_{\substack{S_1, \dots, S_k \subseteq V: \\ S_i \cap S_j = \emptyset, \forall i, j}} \frac{\sum_{h=1, \dots, k} \sum_{(i, j) \in E(S_h, S_h)} A_{i, j} - \frac{1}{k-1} \sum_{h \neq \ell} \sum_{(i, j) \in E(S_h, S_\ell)} A_{i, j}}{\sum_{h \in [k]} |S_h|}.$$

- Because under (i) equally-sized groups and (ii) uniform edge density, # of inter-group edges  $\approx (k-1) \times$  # of intra-group edges.

$$\max_{\mathbf{Y} \in \mathbb{R}^{n \times (k-1)} \setminus \{\mathbf{0}\}} \frac{\text{Tr}(\mathbf{Y}^T \mathbf{A} \mathbf{Y})}{\text{Tr}(\mathbf{Y}^T \mathbf{Y})} \quad (1)$$

$$\text{subject to } Y_{i,j} = \begin{cases} c_j(k-j) & \text{if } i \in S_j \\ 0 & \text{if } i \in \cup_{h=1}^{j-1} S_h \text{ or } i \notin \cup_{h \in [k]} S_h, \text{ where } \{c_j\}_{j \in [k-1]} \text{ are constants.} \\ -c_j & \text{if } i \in \cup_{h=j+1}^k S_h \end{cases}$$

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- Fix  $S_1, \dots, S_{j-1}$ . Find  $S_j = \{i \in [n] : \mathbf{u}_i^* = k - j\}$  by solving

$$\mathbf{u}^* \in \operatorname{argmax} \left\{ \frac{\mathbf{x}^T \mathbf{A}^{(j-1)} \mathbf{x}}{\mathbf{x}^T \mathbf{x}} : \mathbf{x} \in \{-1, 0, k - j\}^n \setminus \{\mathbf{0}\} \right\}, \quad (2)$$

where  $\mathbf{A}^{(j-1)}$  is the adj. matrix after removing  $\cup_{h \in [j-1]} S_h$  and  $\mathbf{A}^{(0)} = \mathbf{A}$ .

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- Eigenvector-based: let  $\mathbf{u}$  be the leading eigenvector of  $\mathbf{A}^{(j-1)}$ .  
Randomized rounding:  $\mathcal{O}((k - j)\sqrt{n})$ -approx generalizes [BGG<sup>+</sup>19]

$$\tilde{\mathbf{u}}_i = \begin{cases} (k - j) \cdot \text{Bernoulli}(|\mathbf{u}_i| / (k - j)) & \text{if } \mathbf{u}_i > 0 \\ -1 \cdot \text{Bernoulli}(|\mathbf{u}_i|) & \text{if } \mathbf{u}_i < 0 \end{cases}$$

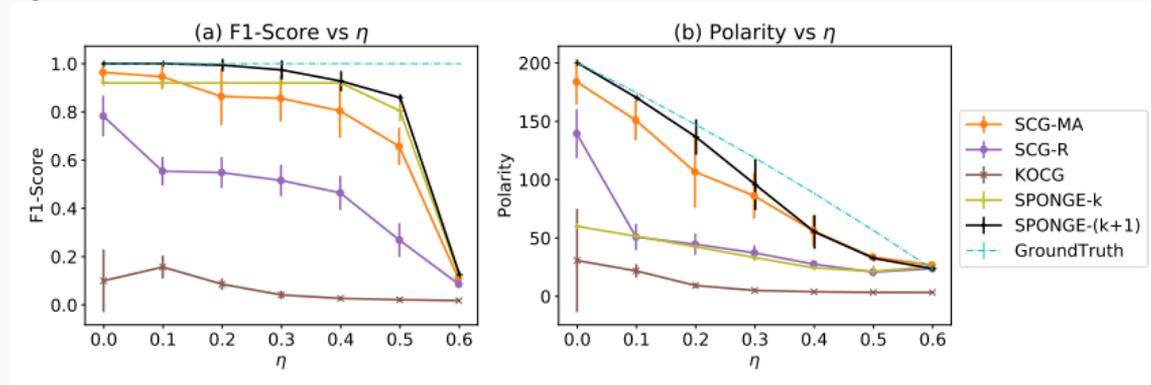
[TOG20] There exists an instance such that the integrality gap of any eigenvector-based algorithm is  $\Omega(\sqrt{n})$ .

# Experiment results

## Real-world networks:

	Bitcoin	WikiVote	Referendum	Slashdot	WikiConflict	Epinions	Wikipolitics
$ V $	5881	7115	10884	82140	116717	131580	138587
$ E $	21492	100693	251406	500481	2026646	711210	715883
$ E_- / E $	0.2	0.2	0.1	0.2	0.6	0.2	0.1
SCG-MA	<b>14.6</b>	<b>45.5</b>	<b>84.9</b>	<b>37.8</b>	<b>102.6</b>	<b>88.8</b>	<b>57.5</b>
SCG-R	5.0	9.7	39.8	7.3	16.2	39.4	5.5
KOCC [CWP <sup>+</sup> 16]	4.4	5.5	8.8	2.6	4.5	8.7	4.8
SPONGE-k [CDGT19]	5.0	15.8	41.5	—	—	—	—
SPONGE-(k+1) [CDGT19]	0.8	1.0	1.0	—	—	—	—

## Synthetic:



- Can the approximation guarantee of (2) be improved?

$$\mathbf{u}^* \in \operatorname{argmax} \left\{ \frac{\mathbf{x}^T \mathbf{A} \mathbf{x}}{\mathbf{x}^T \mathbf{x}} : \mathbf{x} \in \{-1, 0, q\}^n \setminus \{\mathbf{0}\} \right\}. \quad (2)$$

- Is it possible to design an algorithm with provable guarantee to the  $k$ -conflicting group detection?
- What is the fundamental limit in detecting  $k$ -conflicting groups in the synthetic model?

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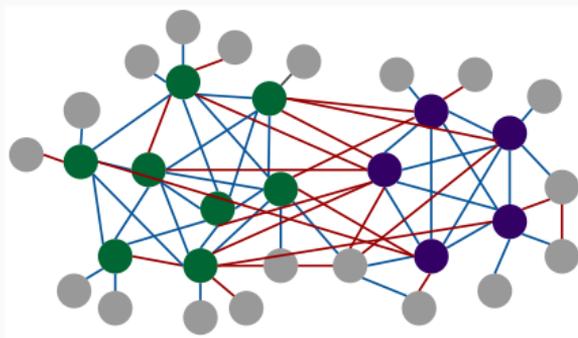
- Given a symmetric matrix  $\mathbf{A}$ , we study the leading eigenvector  $\mathbf{u}$  returned by Randomized SVD (RSVD) w.r.t.  $R(\mathbf{u}) = \frac{\mathbf{u}^T \mathbf{A} \mathbf{u}}{\lambda_1}$ , where  $\lambda_1$  is  $\mathbf{A}$ 's leading eigenvalue
- By relating  $R(\mathbf{u})$  with random projection lemma, we sharpen the analysis of RSVD in the pass-efficient setting

## Multiplicative analysis of RSVD using $R(\mathbf{u})$

- Given a symmetric matrix  $\mathbf{A}$ , let  $\mathbf{u}$  be the leading eigenvector returned by RSVD using  $\mathcal{O}(dn)$ -memory and  $q$  passes over  $\mathbf{A}$
- We analyze  $\mathbf{u}$  w.r.t.

$$R(\mathbf{u}) = \lambda_1^{-1}(\mathbf{A}) \frac{\mathbf{u}^T \mathbf{A} \mathbf{u}}{\mathbf{u}^T \mathbf{u}}$$

- Motivation: the **2-conflicting-group-detection** algorithm [BGG<sup>+</sup>19] is  $\mathcal{O}(R(\mathbf{u})^{-1} \sqrt{n})$ -approx by rounding  $\mathbf{u}$



- Prior to our [TWA<sup>+</sup>22]: for any  $\mathbf{A} \succcurlyeq 0$ , w.p.  $\geq 1 - e^{-\Omega(d)}$ ,

$$\frac{\text{no guarantee } R(\hat{\mathbf{u}}) = \Omega(1)}{o(\ln n)\text{-pass}} \mid \frac{\Omega(\ln n)\text{-pass}}{\Omega(\ln n)\text{-pass}} \rightarrow q$$

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- Our contribution: for any  $\mathbf{A} \succcurlyeq 0$ , w.p.  $\geq 1 - e^{-\Omega(d)}$ ,

$$\frac{R(\hat{\mathbf{u}}) = \Omega\left(\left(\frac{d}{n}\right)^{\frac{1}{2q+1}}\right)}{o(\ln n)\text{-pass} \quad \Omega(\ln n)\text{-pass}} \rightarrow q$$

and for some indefinite  $\mathbf{A}$ , w.p.  $\geq 1 - e^{-\Omega(\sqrt{d})}$ ,

$$\frac{R(\hat{\mathbf{u}}) = \Omega\left(\left(\frac{d}{n}\right)^{\frac{1}{2q+1}}\right)}{o(\ln n)\text{-pass} \quad \Omega(\ln n)\text{-pass}} \rightarrow q$$

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### Algorithm 1: RSVD ( $\mathbf{A}$ , $q$ , $d$ )

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- 1  $\mathbf{Y} \leftarrow \mathbf{A}^q \mathbf{S}$  where  $\mathbf{S} \sim \mathcal{N}(0, 1)^{n \times d}$ ;
  - 2  $\mathbf{Y} = \mathbf{QR}$ ;
  - 3  $\mathbf{B} \leftarrow \mathbf{Q}^T \mathbf{A} \mathbf{Q}$ ;
  - 4  $\hat{\mathbf{u}} = \mathbf{Q} \mathbf{u}_1(\mathbf{B})$ ;
  - 5 return  $\hat{\mathbf{u}}$ ;
- 

(Step 1: line 1)  $\mathbf{Y}_{:,j} = \mathbf{A}^q \mathbf{S}_{:,j} = \sum_{i=1}^n \lambda_i^q (\mathbf{u}_i^T \mathbf{S}_{:,j}) \mathbf{u}_i, \forall j \in [d]$

(Step 2: line 2-4)  $\hat{\mathbf{u}} = \operatorname{argmax}\{\mathbf{v}^T \mathbf{A} \mathbf{v} : \mathbf{v} \in \operatorname{range}(\mathbf{Y}) \cap \mathbb{S}^{n-1}\}$

Effect of  $q \uparrow$ :  $\mathbf{Y}_{:,j}$  align more to eigenspace of  $\lambda_1$

Effect of  $d \uparrow$ : (i)  $\uparrow$  concentration around  $\mathbb{E}[R(\mathbf{Y}_{:,j})]$ ; (ii)  $\uparrow \mathbb{E}[R(\hat{\mathbf{u}})]$

- We relate  $R(\hat{\mathbf{u}})$  with random projection length by Cauchy-Schwarz inequality:

$$\underbrace{\max_{\mathbf{a} \in \mathbb{S}^{d-1}} \frac{\sum_{i \in [n]} \alpha_i^{2q+1} \langle \mathbf{S}^T \mathbf{u}_i, \mathbf{a} \rangle^2}{\sum_{i \in [n]} \alpha_i^{2q} \langle \mathbf{S}^T \mathbf{u}_i, \mathbf{a} \rangle^2}}_{R(\hat{\mathbf{u}})} \implies \underbrace{\max_{\mathbf{a} \in \mathbb{S}^{d-1}} \frac{\langle \mathbf{S}^T \mathbf{u}_1, \mathbf{a} \rangle^2}{\sum_{i \in [n]} \langle \mathbf{S}^T \mathbf{u}_i, \mathbf{a} \rangle^2}}_{\cos^2 \theta(\mathbf{u}_1, \mathbf{S})},$$

where  $\alpha_i = \frac{\lambda_i}{\lambda_1}, \forall i \in [n]$

- **(Lemma [Ver18])**  $\forall \mathbf{v} \in \mathbb{S}^{n-1}$  and  $d \ll n$ , w.p.  $\geq 1 - e^{-\Omega(d)}$ ,

$$\cos^2 \theta(\mathbf{v}, \mathbf{S}) = \Theta\left(\frac{d}{n}\right).$$

**(Theorem 1)**  $\forall \mathbf{A} \succcurlyeq 0$ ,  $R(\hat{\mathbf{u}}) = \left(\Omega\left(\frac{d}{n}\right)\right)^{\frac{1}{2q+1}}$  w.p.  $\geq 1 - e^{-\Omega(d)}$ .

**(Theorem 2)**  $\exists \mathbf{A} \succcurlyeq 0$  s.t.  $R(\hat{\mathbf{u}}) = \mathcal{O}\left(\left(\frac{d}{n}\right)^{\frac{1}{2q+1}}\right)$  w.p.  $\geq 1 - e^{-\Omega(d)}$ .

**(Theorem 3)**  $\forall \mathbf{A} \succcurlyeq 0$  with  $(i_0, \gamma)$ -power-law decay,  $i_0 \in [n]$  and  $\gamma > 1/2q$ ,

$$R(\hat{\mathbf{u}}) = \Omega\left(\left(\frac{d}{d+i_0}\right)^{\frac{1}{2q+1}}\right) \text{ w.p. } \geq 1 - e^{-\Omega(d)}.$$

**(Assumption 1)**  $\exists \kappa \in (0, 1]$  s.t.  $\sum_{i=2}^n \lambda_i^{2q+1} \geq \kappa \sum_{i=2}^n |\lambda_i|^{2q+1}$ .

**(Theorem 4)**  $\forall \mathbf{A}$  with  $(i_0, \gamma)$ -power-law decay,  $i_0 \in [n]$  and  $\gamma > 1/2q$ , and satisfying Assumption 1, there exists a constant  $c_\kappa > 0$  such that

$$R(\hat{\mathbf{u}}) = \Omega\left(c_\kappa \left(\frac{d}{d+i_0}\right)^{\frac{1}{2q+1}}\right) \text{ w.p. } \geq 1 - e^{-\Omega(\sqrt{d}\kappa^2)}.$$

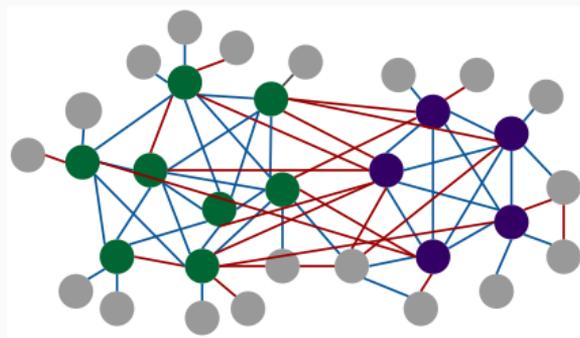
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**Algorithm 2:** RandSum( $\mathbf{A}$ ,  $q$ ,  $d$ ,  $p$ )

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- 1  $\mathbf{S}_1 \sim \mathcal{N}(0, 1)^{n \times \lceil \frac{d}{2} \rceil}$ ,  $\mathbf{S}_2 \sim \text{Bernoulli}(p)^{n \times \lfloor \frac{d}{2} \rfloor}$ ;
  - 2  $\mathbf{S} \leftarrow [\mathbf{S}_1 \quad \mathbf{S}_2]$ ;
  - 3 return RSVD( $\mathbf{A}, \mathbf{S}, q, d$ );
- 

- **Motivation:** Consider the case when  $\langle \mathbf{u}_1, \mathbf{1}_n \rangle = \Theta(\sqrt{n})$ :



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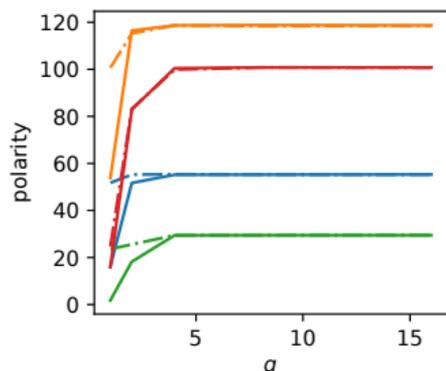
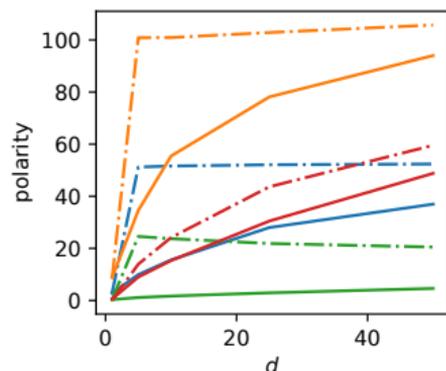
- **(Theorem 5)** For  $\mathbf{A} \succcurlyeq 0$ , RandSum( $\mathbf{A}, q, d, p$ ) returns  $\hat{\mathbf{u}}$  satisfying

$$R(\hat{\mathbf{u}}) = \left( \Omega \left( \frac{\max \{d, \langle \mathbf{u}_1, \mathbf{1}_n \rangle^2\}}{n} \right) \right)^{\frac{1}{2q+1}} \quad \text{with prob. } \geq 1 - e^{-\Omega(d)}.$$

**Theorem 5** extends to some indefinite  $\mathbf{A}$  under an assumption similar to **Assumption 1**.

## Experimental results

	WikiVot	Referendum	Slashdot	WikiCon
$ V $	7 115	10 884	82 140	116 717
$ E $	100 693	251 406	500 481	2 026 646
$(\gamma, i_0)$	(4.6, 15)	(4.5, 16)	(5.3, 17)	(2.8, 22)
$\kappa$	0.397	0.620	0.204	0.034
$\cos \theta(\mathbf{u}_1, \mathbf{1}_n)$	0.378	0.399	0.194	0.193



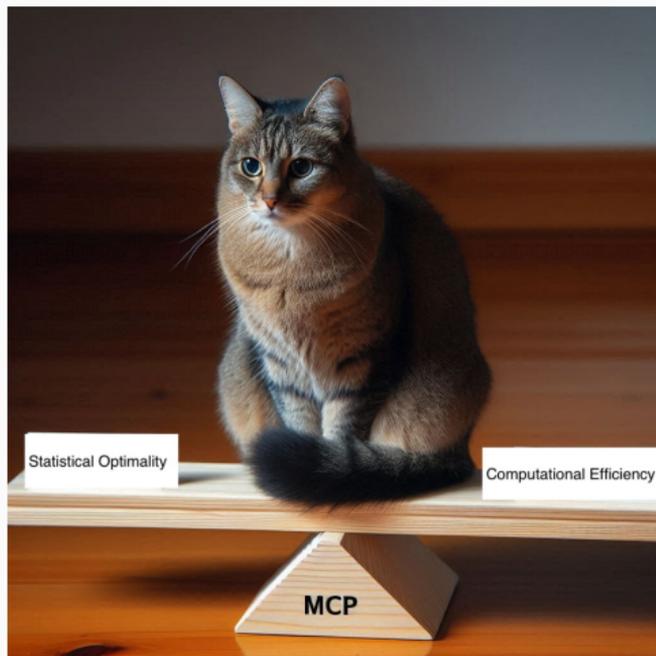
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- Do the results generalize to (row/column)-stochastic matrices?
- Do the results of `RandSum` hold for other non-centered subgaussian distributions?
- Can we extend the analysis to top- $k$  eigenvectors approximations?
- What is the fundamental limit of  $R(\hat{\mathbf{u}})$  for any  $q$ -pass  $\tilde{O}(n)$ -space algorithm?
- Can we reduce the space complexity while keeping the same guarantees?

## **Part II - Combinatorial MAB: implicit structure exploitation**

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- [TOA24] "Matroid Semi-bandits in Sublinear Time." In Proc. of ICML 2024.

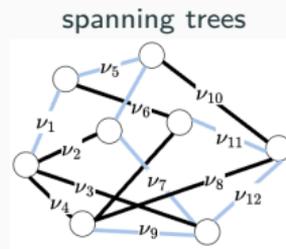
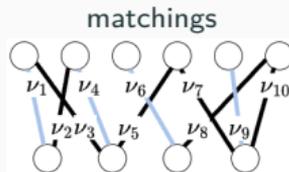
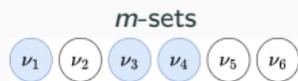


- We show there is no **computational-statistical** gap for combinatorial BAI with fixed confidence and semi-bandit feedback
- The main bottleneck is the computation for the most confusing parameter (**MCP**)
- We propose an approximate **MCP** algorithm and use it to design an optimal algorithm that runs in poly. time

# Combinatorial semi-bandits

Given

- $K$  arms  $(\nu_k)_{k \in [K]}$  with mean  $\mu \in \mathbb{R}^K$
- Set  $\mathcal{X} \subseteq \{0, 1\}^K$  of actions



In round  $t$ , a learner

- pulls action  $\mathbf{x}(t) \in \mathcal{X}$
- receives the reward  $y_k(t) \sim \nu_k(t)$  if  $x_k(t) = 1$

Sequential sampling strategy:  $\mathbf{x}(t) \in \mathcal{F}_t := \sigma(\mathbf{x}(1), \mathbf{y}(1), \dots, \mathbf{x}(t-1), \mathbf{y}(t-1))$ .

**Goal:** identify the best action  $i^*(\mu) \in \operatorname{argmax}_{x \in \mathcal{X}} \langle \mathbf{x}, \mu \rangle$ .

A strategy consist of

- (sampling rule)  $\mathbf{x}(t) \in \mathcal{F}_t$  (action to explore)
- (stopping rule)  $\tau$  (round to stop)
- (decision rule)  $\mathcal{F}_\tau$ -measurable  $\hat{i} \in \mathcal{X}$  (guess of best action to return)

Wish to minimize  $\mathbb{E}_\mu[\tau]$  subject to  $\mathbb{P}_\mu[\hat{i} \neq i^*(\mu)] \leq \delta$ .

Throughout this work, we assume

- (i)  $\forall \boldsymbol{\mu} \in \Lambda$ ,  $\mathbf{i}^*(\boldsymbol{\mu})$  is **unique**, where  $\Lambda$  denotes all possible parameters.
- (ii)  $\forall k \in [K]$ , arm  $k$ 's reward distribution is  $\nu_k = \mathcal{N}(\mu_k, 1)$ .
- (iii)  $\forall \mathbf{v} \in \mathbb{R}^K$ ,  $\mathbf{i}^*(\mathbf{v})$  can be found in **poly. time**.
- (iv)  $\mathcal{X}$  is **inclusion-wise maximal**, i.e., no  $\mathbf{x}, \mathbf{x}' \in \mathcal{X}$  such that  $\mathbf{x} < \mathbf{x}'$

Here  $\mathbf{i}^*(\mathbf{v}) \in \operatorname{argmax}_{\mathbf{x} \in \mathcal{X}} \langle \mathbf{x}, \mathbf{v} \rangle$ .

# A standard way to design a statistically optimal algorithm

[GK16] showed that: for any  $\delta$ -PAC algorithm (stop in finite time a.e. and  $\mathbb{P}_{\mu}[\hat{i} \neq i^*(\mu)] \leq \delta$ ),

$$\liminf_{\delta \rightarrow 0} \frac{\mathbb{E}_{\mu}[\tau]}{\ln(1/\delta)} \geq \left( \sup_{\omega \in \Sigma} \inf_{\lambda \in \text{Alt}(\mu)} \sum_{k=1}^K \frac{\omega_k (\mu_k - \lambda_k)^2}{2} \right)^{-1}. \quad (3)$$

- $\Sigma = \{\sum_{x \in \mathcal{X}} w_x \mathbf{x} : \mathbf{w} \in \Sigma_{|\mathcal{X}|}\}$ : all possible arm allocations
- $\text{Alt}(\mu) = \{\lambda \in \Lambda : i^*(\lambda) \neq i^*(\mu)\}$ : confusing parameters

(3)  $\Rightarrow$  An optimal algorithm has a sampling strategy described by

$$\hat{\omega}(t) \xrightarrow{t \rightarrow \infty} \omega^*(\mu) := \arg \max_{\omega \in \Sigma} F_{\mu}(\omega),$$

where  $\hat{\omega}(t)$  is the empirical allocation of arm draws up to round  $t$ , and

$$F_{\mu}(\omega) = \inf_{\lambda \in \text{Alt}(\mu)} \sum_{k=1}^K \frac{\omega_k (\mu_k - \lambda_k)^2}{2}.$$

- most confusing parameter (MCP):  $\arg \inf_{\lambda \in \text{Alt}(\mu)} \sum_{k=1}^K \frac{\omega_k (\mu_k - \lambda_k)^2}{2}$



# A standard way to design a statistically optimal algorithm

A standard way [GK16] consists of:

- (sampling rule) pull an action by tracking  $\operatorname{argmax}_{\omega \in \Sigma} F_{\hat{\mu}(t)}(\omega)$
- (stopping rule) Generalized Likelihood Ratio Test (GLRT):

$$\tau = \inf \left\{ t : t F_{\hat{\mu}(t)}(\hat{\omega}(t)) > \ln \left( \frac{t}{\delta} \right) + o(1) \right\} \quad (4)$$

- (decision rule) return  $\hat{i} \leftarrow i^*(\hat{\mu}(\tau))$

where  $\hat{\mu}(t)$  is the estimate of  $\mu$ , and  $\hat{\omega}(t)$  is the empirical pulled arm allocation up to  $t$

## Difficulty in identifying MCP (or equivalently $F(\cdot)$ )

Prior approach is to solve  $|\mathcal{X}| - 1$  many convex programs by partitioning

$$\text{Alt}(\mu) = \cup_{\mathbf{x} \neq i^*(\mu)} \{ \lambda \in \Lambda : \langle i^*(\mu) - \mathbf{x}, \lambda \rangle < 0 \}$$

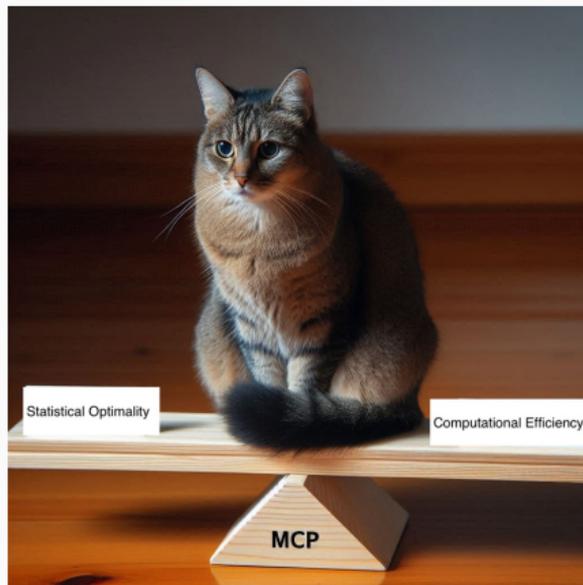
However,  $|\mathcal{X}| = \mathcal{O}(2^K)$ !



# Other statistically optimal sampling rules

In addition to the GLRT stopping rule, MCP is also required by

- FWS [WTP21]: apply the first-order methods to maximize  $F_{\mu}(\omega)$ , where the gradient is derived by a MCP (Envelop theorem), and enlarge the subdifferential to cope with non-smoothness .
- CombGame [JMKK21]: need a MCP for chasing a saddle point.



- P-FWS copes with non-smoothness actions by *stochastic smoothing*.
- All P-FWS needs are
  - (i) linear maximization oracle  $\mathbf{i}^*(\cdot)$  (standard),
  - (ii)  $(\epsilon, \theta)$ -MCP, where  $\epsilon > 0, \theta \in (0, 1)$  (established in this work).

## Roadmap

1. Designing the  $(\epsilon, \theta)$ -MCP oracle
2. Solving lowerbound problem  $\sup_{\omega \in \Sigma} F_{\mu}(\omega)$  by P-FWS

# 1. Designing the approximate MCP oracle

Let  $\mathbf{x} \neq \mathbf{i}^*(\boldsymbol{\mu})$ , define  $f_{\mathbf{x}}(\boldsymbol{\omega}, \boldsymbol{\mu}) = \inf_{\boldsymbol{\lambda} \in \mathbb{R}^K: \langle \mathbf{i}^*(\boldsymbol{\mu}) - \mathbf{x}, \boldsymbol{\lambda} \rangle < 0} \sum_{k=1}^K \frac{\omega_k (\mu_k - \lambda_k)^2}{2}$ .

## Property of $f_{\mathbf{x}}$ and its Lagrangian dual $g_{\boldsymbol{\omega}, \boldsymbol{\mu}}$

$$f_{\mathbf{x}}(\boldsymbol{\omega}, \boldsymbol{\mu}) = \max_{\alpha \geq 0} g_{\boldsymbol{\omega}, \boldsymbol{\mu}}(\mathbf{x}, \alpha) \text{ (strong duality)}$$

$g_{\boldsymbol{\omega}, \boldsymbol{\mu}}(\mathbf{x}, \alpha)$  is *linear* in  $\mathbf{x}$  and *concave* in  $\alpha$

$$\Rightarrow F_{\boldsymbol{\mu}}(\boldsymbol{\omega}) = \min_{\mathbf{x} \neq \mathbf{i}^*(\boldsymbol{\mu})} f_{\mathbf{x}}(\boldsymbol{\omega}, \boldsymbol{\mu}) = \min_{\mathbf{x} \neq \mathbf{i}^*(\boldsymbol{\mu})} \max_{\alpha \geq 0} g_{\boldsymbol{\omega}, \boldsymbol{\mu}}(\mathbf{x}, \alpha) \quad (5)$$

(5) motivates us a design:

- **x-player** employs a regret min. algorithm to **minimize**  $g_{\boldsymbol{\omega}, \boldsymbol{\mu}}(\mathbf{x}, \alpha)$
- **$\alpha$ -player** employs a regret min. algorithm to **maximize**  $g_{\boldsymbol{\omega}, \boldsymbol{\mu}}(\mathbf{x}, \alpha)$

# 1. Designing the approximate MCP oracle

However, the choices are limited since...

1.  $\{\mathbf{x} \neq \mathbf{i}^*(\boldsymbol{\mu})\}$  is a discrete set which consist of  $\mathcal{O}(2^K)$  elements
2. min max = max min could not hold
3. we need the *equilibrium action*  $\mathbf{x}_e$  s.t.  $F_{\boldsymbol{\mu}}(\boldsymbol{\omega}) = \max_{\alpha \geq 0} g_{\boldsymbol{\omega}, \boldsymbol{\mu}}(\mathbf{x}_e, \alpha)$
4. we want computationally efficient algorithms, i.e. approximate  $\mathbf{x}_e$  in polynomial time

# 1. Designing the approximate MCP oracle

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## Algorithm 3: $(\epsilon, \theta)$ -MCP( $\omega, \mu$ )

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1 **for**  $n = 1, 2, \dots$  **do**  
2     (Follow-the-Perturbed-Leader)  $\mathcal{Z}_n \sim \exp(1)^K$  and  $\eta_n = \frac{c_0}{\sqrt{n}}$   
          
$$\mathbf{x}^{(n)} \in \operatorname{argmin}_{\mathbf{x} \neq \mathbf{i}^*(\mu)} \left( \sum_{m=1}^{n-1} g_{\omega, \mu}(\mathbf{x}, \alpha^{(m)}) + \frac{\langle \mathcal{Z}_n, \mathbf{x} \rangle}{\eta_n} \right)$$
  
          (Best-Response)  $\alpha^{(n)} \in \operatorname{argmax}_{\alpha \geq 0} g_{\omega, \mu}(\mathbf{x}^{(n)}, \alpha)$   
3     **if**  $\sqrt{n} > \frac{c_\theta(1 + \epsilon)}{\epsilon \hat{F}}$ , where  $\begin{cases} \hat{F} = g_{\omega, \mu}(\mathbf{x}^{(n_*)}, \alpha^{(n_*)}) \\ n_* \in \operatorname{argmin}_{m \leq n} g_{\omega, \mu}(\mathbf{x}^{(m)}, \alpha^{(m)}) \end{cases}$  **then return**  
           $(\hat{F}, \mathbf{x}^{(n_*)})$ ;  
4 **end**

---

# 1. Designing the approximate MCP oracle

## Theorem 1 (MCP)

Let  $(\omega, \mu) \in \Sigma_+ \times \Lambda$ . The  $(\epsilon, \theta)$ -MCP( $\omega, \mu$ ) algorithm outputs  $(\hat{F}, \hat{x})$ :

- $\mathbb{P}\left[F_\mu(\omega) \leq \hat{F} \leq (1 + \epsilon)F_\mu(\omega)\right] \geq 1 - \theta$
- the number of calls to  $i^*(\cdot)$ :  $\mathcal{O}\left(\frac{\|\mu\|_\infty^4 \|\omega^{-1}\|_\infty^2 K^3 D^5 \ln K \ln \theta^{-1}}{\epsilon^2 F_\mu(\omega)^2}\right)$

By envelop theorem [WTP21], we estimate the (sub)gradient of  $F_\mu(\omega)$  by

$$\nabla_\omega f_{\hat{x}}(\omega, \mu) = \left( \frac{(\mu_k - \lambda_k^*)^2}{2} \right)_{k \in [K]},$$

where  $\lambda^*$  is the minimizer to the optimization problem of  $f_{\hat{x}}(\omega, \mu)$ .

## 2. Solving the lowerbound problem $\max_{\omega \in \Sigma} F_{\mu}(\omega)$

$F_{\mu}$  is nonsmooth  $\Rightarrow$  using stochastic smoothing [FKM05, DBW12],

$\bar{F}_{\mu, \eta}(\omega) = \mathbb{E}_{\mathcal{Z} \sim \text{Uniform}(B_2)}[F_{\mu}(\omega + \eta \mathcal{Z})]$  with noise level  $\eta > 0$  satisfies:

- $\nabla \bar{F}_{\mu, \eta}(\omega) = \mathbb{E}_{\mathcal{Z} \sim \text{Uniform}(B_2)}[\nabla F_{\mu}(\omega + \eta \mathcal{Z})]$
- $\bar{F}_{\mu, \eta}$  is  $\frac{\ell K}{\eta}$ -smooth and  $\bar{F}_{\mu, \eta}(\omega) \xrightarrow{\eta \downarrow 0} F_{\mu}(\omega)$

### High-level design of P-FWS

Let  $\mathcal{X}_0$  be a set s.t.  $\forall k \in [K]$ , there exists  $\mathbf{x} \in \mathcal{X}_0$  s.t.  $x_k = 1$ .

P-FWS alternate between two phases:

- pull each  $\mathbf{x} \in \mathcal{X}_0$  once (to avoid high cost and boundary cases)
- pull  $\mathbf{x}(t) \in \operatorname{argmax}_{\mathbf{x} \in \mathcal{X}} \langle \nabla \bar{F}_{\hat{\mu}(t-1), \eta_t}(\hat{\omega}(t-1)), \mathbf{x} \rangle$  (ideal FW update)



## 2. Solving the lowerbound problem $\max_{\omega \in \Sigma} F_{\mu}(\omega)$

### Theorem 2 (P-FWS)

Let  $\mu \in \Lambda$  and  $\delta \in (0, 1)$ . P-FWS is  $\delta$ -PAC, and

- (i)  $\limsup_{\delta \rightarrow 0} \frac{\mathbb{E}_{\mu}[\tau]}{\ln(1/\delta)} \leq \left( \sup_{\omega \in \Sigma} \inf_{\lambda \in \text{Alt}(\mu)} \sum_{k=1}^K \frac{\omega_k (\mu_k - \lambda_k)^2}{2} \right)^{-1}$
- (ii)  $\mathbb{E}_{\mu}[\tau] = \text{poly}(K)$  in moderate confidence regime
- (iii) the expected number of calls for linear maximization is upper bounded by  $\text{poly}(K)$

**Note:** To our best knowledge, (ii) is even not yet established in unstructured BAI.

- P-FWS closes the computational-statistical gap for combinatorial BAI by exploring the structural properties of the lowerbound problem, and it shows strong empirical performance:

Algorithm	Sample Complexity
P-FWS (ours)	1 176
CombGame [JMKK21]	1 277

**Table 1:** Averaged sample complexity at  $\delta = 0.1$  over 100 independent runs on a graph with  $|\mathcal{X}| = 21\,025$  spanning trees.

- The computational-statistical gap widely exists for other tasks

**Table 2:** Computational-statistical gap in combinatorial semi-bandits.

	Reward Distribution	Statistical Optimality	Computational Efficiency & Statistical Optimality
Combinatorial BAI (semi-bandit)	Gaussian Bernoulli	[JMKK21, WTP21]	[TWPL23] open
Combinatorial BAI (full-bandit)	Gaussian Bernoulli	[WTP21]	open
Combinatorial Regret Minimization	Gaussian Bernoulli	[CMP17]	open

For graph mining,

- [TOG20]: solve a discrete Rayleigh's quotient maximization problem
- [TWA<sup>+</sup>22]: sharpen the analysis of Randomized SVD for the ratio objective

For combinatorial semi-bandits,

- [TWPL23]: close the computational-statistical gap for combinatorial BAI with fixed-confidence
- [TOA24]: design the first sublinear-time algorithm for the matroid semi-bandits



- We study the matroid semi-bandit problem and propose an algorithm that runs in sublinear time while matching the gap-dependent regret lower bound asymptotically
- The main technique is rounding and the minimum hitting set.

- Given an instance of matroid semi-bandit  $([K], \mathcal{X}, \boldsymbol{\mu})$ ,
  - $[K] = \{1, \dots, K\}$  is the ground set;
  - $\mathcal{X} \subseteq \{0, 1\}^K$  is the set of bases of  $\mathcal{M} = ([K], \mathcal{I})$ <sup>1</sup>;
  - $\boldsymbol{\mu} \in (0, 1)^K$  is the mean of the arms' rewards  $(\nu_1, \dots, \nu_K)$ <sup>2</sup>;
- At each round  $t$ , the learner pulls  $\mathbf{x}(t) \in \mathcal{X}$  and observes  $y_k(t) \sim \nu_k$  for each arm  $k \in \text{supp}(\mathbf{x}(t))$ .
- The goal is to minimize the expected cumulative regret

$$R(T) = T \langle \mathbf{i}^*, \boldsymbol{\mu} \rangle - \sum_{t=1}^T \mathbb{E}[\langle \mathbf{x}(t), \boldsymbol{\mu} \rangle],$$

where  $\mathbf{i}^* \in \operatorname{argmax}_{\mathbf{x} \in \mathcal{X}} \langle \mathbf{x}, \boldsymbol{\mu} \rangle$ .

---

<sup>1</sup> $\mathcal{I}$  satisfy hereditary property and augmentation property.

<sup>2</sup>We assume for each  $k \in [K]$ , the support of  $\nu_k$  is  $[a, b] \subseteq (0, 1)$ .

- Define  $\Delta_{\min} = \min_{i \in \text{supp}(i^*), j \notin \text{supp}(i^*): \mu_i - \mu_j > 0} (\mu_i - \mu_j)$ .
  - CUCB [KWA<sup>+</sup>14] achieves  $R(T) = \mathcal{O}\left(\frac{(K-D) \log T}{\Delta_{\min}}\right)$ , which matches the gap-dependent LB  $R(T) = \Omega\left(\frac{(K-D) \log T}{\Delta_{\min}}\right)$
  - KL-OSM [TP16] achieves  $\limsup_{T \rightarrow \infty} \frac{R(T)}{\log T} \leq c(\boldsymbol{\mu})$ , matching instance-specific LB  $\liminf_{T \rightarrow \infty} \frac{R(T)}{\log T} \geq c(\boldsymbol{\mu})$ , where  $c(\boldsymbol{\mu}) \leq \frac{K-D}{\Delta_{\min}}$
- Per-round time complexity:
  - CUCB and KL-OSM require at least  $\Omega(K)$
  - CUCB takes  $\mathcal{O}(K(\log K + \mathcal{T}_{\text{member}}))$  and KL-OSM takes  $\mathcal{O}(K(\log K + \mathcal{T}_{\text{member}} + \text{line search}))$ .

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<sup>1</sup> $\mathcal{I}$  satisfy hereditary property and augmentation property.

<sup>2</sup>We assume for each  $k \in [K]$ , the support of  $\nu_k$  is  $[a, b] \subseteq (0, 1)$ .

## Summary of our results

- Nearly optimal per-round time complexity of FasterCUCB on uniform matroid, partition matroid, and graphical matroid
- FasterCUCB has the same regret guarantee as CUCB

	CUCB	FasterCUCB
Per-round Time Complexity	$\mathcal{O}(K(\log K + \mathcal{T}_{\text{member}}))$	$\mathcal{O}(D \text{polylog}(T) \mathcal{T}_{\text{update}}(\mathcal{A}))$
Uniform Matroid	$\mathcal{O}(K \log K)$	$\mathcal{O}(D \log K \text{polylog}(T))$
Partition Matroid	$\mathcal{O}(K \log K)$	$\mathcal{O}(D \log K \text{polylog}(T))$
Graphical Matroid	$\mathcal{O}(K \log K)$	$\mathcal{O}(D \text{polylog}(K) \text{polylog}(T))$
Transversal Matroid	$\mathcal{O}(K(\log K + DK))$	$\mathcal{O}(D\sqrt{K} \text{polylog}(T))$

**Table 3:** Per-round time complexity on different matroids.  $K$  is the number of arms and  $D = \max_{\mathbf{x} \in \mathcal{X}} \|\mathbf{x}\|_0$ .

Let  $\mathbf{f}_k = (\hat{\mu}_k(t-1), \frac{1}{\sqrt{N_k(t-1)}})$  and  $\mathbf{q} = (1, \lambda_t)$ .

$$\mathbf{x}(t) \in \operatorname{argmax}_{\mathbf{x} \in \mathcal{X}} \sum_{k=1}^K \langle \mathbf{f}_k, \mathbf{q} \rangle x_k \quad (\text{CUCB})$$

- CUCB and KL-OSM rely on the following greedy algorithm:
  - (1) Find permutation  $\pi : [K] \rightarrow [K]$  s.t.  $\langle \mathbf{f}_{\pi(k)}, \mathbf{q} \rangle \geq \langle \mathbf{f}_{\pi(k+1)}, \mathbf{q} \rangle, \forall k$
  - (2)  $\mathbf{x} = \mathbf{0}_K$ ; While  $(|\operatorname{supp}(\mathbf{x})| < D)$  If  $(\mathbf{x} + \mathbf{e}_{\pi(k)} \in \mathcal{I})$   $\mathbf{x} = \mathbf{x} + \mathbf{e}_{\pi(k)}$ ;
- Time complexity:  $\mathcal{O}(K(\log K + \mathcal{T}_{\text{member}}))$

Let  $\mathbf{f}_k = (\hat{\mu}_k(t-1), \frac{1}{\sqrt{N_k(t-1)}})$  and  $\mathbf{q} = (1, \lambda_t)$ .

$$\mathbf{x}(t) \in \operatorname{argmax}_{\mathbf{x} \in \mathcal{X}} \sum_{k=1}^K \langle \mathbf{f}_k, \mathbf{q} \rangle x_k \quad (\text{CUCB})$$

- Challenge: Every arm  $k$ 's  $\langle \mathbf{f}_k, \mathbf{q} \rangle$  changes at each round.
- Idea:  $\mathbf{q}$  is "fixed"  $\Rightarrow$  only  $D = \max_{\mathbf{x} \in \mathcal{X}} \|\mathbf{x}\|_0$  arms will change

# Our approach: rounding + minimum hitting set

Let  $\mathbf{f}_k = (\hat{\mu}_k(t-1), \frac{1}{\sqrt{N_k(t-1)}})$  and  $\mathbf{q} = (1, \lambda_t)$ .

$$\mathbf{x}(t) \in \operatorname{argmax}_{\mathbf{x} \in \mathcal{X}} \sum_{k=1}^K \langle \mathbf{f}_k, \mathbf{q} \rangle x_k \quad (\text{CUCB})$$

- Idea:  $\mathbf{q}$  is "fixed"  $\Rightarrow$  only  $D = \max_{\mathbf{x} \in \mathcal{X}} \|\mathbf{x}\|_0$  arms will change
  - [OT23]: Construct a set  $\mathcal{H}$  s.t. for any  $\mathbf{q} \in \mathbb{R}_+^2$ ,  $\exists \mathbf{h} \in \mathcal{H}$  s.t.

$$\langle \mathbf{f}_k, \mathbf{h} \rangle > \langle \mathbf{f}_\ell, \mathbf{h} \rangle \Rightarrow \langle \mathbf{f}_k, \mathbf{q} \rangle \geq \langle \mathbf{f}_\ell, \mathbf{q} \rangle$$

for all possible  $(k, \ell) \in [K] \times [K]$  and  $k \neq \ell$

- For each  $\mathbf{h} \in \mathcal{H}$ , instantiate a dynamic algorithm  $\mathcal{A}_\mathbf{h}$ :
  - fast computation of a maximum-weight base (in  $\mathcal{O}(D)$ -time)
  - fast update of an arm's weight (in  $\mathcal{T}_{\text{update}}$ -time)
- Time complexity:  $\mathcal{O}(D \cdot |\mathcal{H}| \cdot \mathcal{T}_{\text{update}})$  Naive:  $|\mathcal{H}| = \mathcal{O}(K^2)$



# Our approach: rounding + minimum hitting set

Let  $\mathbf{f}_k = (\hat{\mu}_k(t-1), \frac{1}{\sqrt{N_k(t-1)}})$  and  $\mathbf{q} = (1, \lambda_t)$ .

$$\mathbf{x}(t) \in \operatorname{argmax}_{\mathbf{x} \in \mathcal{X}} \sum_{k=1}^K \langle \mathbf{f}_k, \mathbf{q} \rangle x_k \quad (\text{CUCB})$$

- **(Rounding)** Generate  $\text{polylog}(T)$  bins with  $\epsilon = \frac{1}{\log^m T}$ .

Represent each  $\text{BIN}(q, r) = (a(1+\epsilon)^{q-1}, a(1+\epsilon)^q] \times (\frac{(1+\epsilon)^{r-1}}{\sqrt{T}}, \frac{(1+\epsilon)^r}{\sqrt{T}}]$  by  $\text{dom}_{q,r} = (a(1+\epsilon)^q, \frac{1}{\sqrt{T}}(1+\epsilon)^r)$ .

$$\forall \mathbf{f} \in \text{BIN}(q, r), \quad \frac{\langle \text{dom}_{q,r}, \mathbf{q} \rangle}{1+\epsilon} < \langle \mathbf{f}, \mathbf{q} \rangle \leq \langle \text{dom}_{q,r}, \mathbf{q} \rangle, \quad (6)$$

- **(Hitting set)** Generate  $\mathcal{H}$  of size  $\text{polylog}(T)$  s.t.  $\forall \mathbf{q} \in \mathbb{R}_+^2, \exists \mathbf{h} \in \mathcal{H}$  s.t.

$$\langle \text{dom}_{q,r}, \mathbf{h} \rangle > \langle \text{dom}_{q',r'}, \mathbf{h} \rangle \Rightarrow \langle \text{dom}_{q,r}, \mathbf{q} \rangle \geq \langle \text{dom}_{q',r'}, \mathbf{q} \rangle \quad (7)$$

for any  $(q, r) \neq (q', r')$ , and  $\mathbf{h}$  can be found in  $\text{polylog}(T)$  time.



## Our approach: rounding + minimum hitting set

Let  $\mathbf{f}_k = (\hat{\mu}_k(t-1), \frac{1}{\sqrt{N_k(t-1)}})$  and  $\mathbf{q} = (1, \lambda_t)$ .

$$\mathbf{x}(t) \in \operatorname{argmax}_{\mathbf{x} \in \mathcal{X}} \sum_{k=1}^K \langle \mathbf{f}_k, \mathbf{q} \rangle x_k \quad (\text{CUCB})$$

### Initialization:

- Generate polylog( $T$ ) bins
- Generate the minimum hitting set  $\mathcal{H}$  of size polylog( $T$ )
- For each  $\mathbf{h} \in \mathcal{H}$ , instantiate a dynamic algorithm  $\mathcal{A}_{\mathbf{h}}$  with arm  $k$ 's weight  $\langle \operatorname{dom}(\mathbf{f}_k), \mathbf{h} \rangle$

### FindBase( $\mathbf{q}$ ): Find $\mathbf{h} \in \mathcal{H}$ such that

$$\langle \operatorname{dom}_{q,r}, \mathbf{h} \rangle > \langle \operatorname{dom}_{q',r'}, \mathbf{h} \rangle \Rightarrow \langle \operatorname{dom}_{q,r}, \mathbf{q} \rangle \geq \langle \operatorname{dom}_{q',r'}, \mathbf{q} \rangle$$

Call  $\mathcal{A}_{\mathbf{h}}$  to output a  $(1 + \epsilon)$ -approx maximum-weight base

### UpdateFeature( $\mathbf{f}, k$ ): $\forall \mathbf{h} \in \mathcal{H}$ , update $k$ 's weight to $\langle \operatorname{dom}(\mathbf{f}), \mathbf{h} \rangle$



Let  $\mathbf{f}_k = (\hat{\mu}_k(t-1), \frac{1}{\sqrt{N_k(t-1)}})$  and  $\mathbf{q} = (1, \lambda_t)$ .

$$\mathbf{x}(t) \in \operatorname{argmax}_{\mathbf{x} \in \mathcal{X}} \sum_{k=1}^K \langle \mathbf{f}_k, \mathbf{q} \rangle x_k \quad (\text{CUCB})$$

- **FasterCUCB:** At round  $t$ ,
  - Compute  $\mathbf{x}(t)$  by **FindBase**( $\mathbf{q}$ )
  - For each  $k \in \operatorname{supp}(\mathbf{x}(t))$ , observe  $y_k(t) \sim \nu_k$  and **UpdateFeature**( $(\frac{(t-1)\mu_k(t-1) + y_k(t)}{t}, \frac{1}{\sqrt{N_k(t-1)+1}})$ ,  $k$ )
- Time complexity:  $\mathcal{O}(D \operatorname{polylog}(T) \mathcal{T}_{\text{update}}(\mathcal{A}))$
- Regret upper bound:  $\lim_{T \rightarrow \infty} \frac{R(T)}{\log T} = \mathcal{O}\left(\frac{K-D}{\Delta_{\min}}\right)$ .

- **(Challenge)**  $x(t) \leftarrow \text{FindBase}(q)$  is a  $(1 + \epsilon)$ -approx to the maximum weight base

- Fix  $\mathbf{i}^* \in \operatorname{argmax}_{\mathbf{x} \in \mathcal{X}} \langle \mathbf{x}, \boldsymbol{\mu} \rangle$  and let  $\Delta_{j,k} = \mu_j - \mu_k$
- Construct a bijection  $g_t : \operatorname{supp}(\mathbf{i}^*) \mapsto \operatorname{supp}(\mathbf{x}(t))$  such that
  - if  $j \in \operatorname{supp}(\mathbf{i}^*) \cap \operatorname{supp}(\mathbf{x}(t))$ , then  $g_t(j) = j$
  - if  $j \in \operatorname{supp}(\mathbf{i}^*) \setminus \operatorname{supp}(\mathbf{x}(t))$ , then  $(1 + \epsilon) \underbrace{\langle \mathbf{f}_{g_t(j)}, \mathbf{q} \rangle}_{\text{UCB index of arm } g_t(j)} \geq \underbrace{\langle \mathbf{f}_j, \mathbf{q} \rangle}_{\text{UCB index of arm } j}$
- $R(T) = \sum_{k \notin \operatorname{supp}(\mathbf{i}^*)} \sum_{j \in \operatorname{supp}(\mathbf{i}^*)} \Delta_{j,k} \sum_{t=1}^T \mathbb{P}[g_t(j) = k]$

- Fix  $\mathbf{i}^* \in \operatorname{argmax}_{\mathbf{x} \in \mathcal{X}} \langle \mathbf{x}, \boldsymbol{\mu} \rangle$  and let  $\Delta_{j,k} = \mu_j - \mu_k$
- Construct a bijection  $g_t : \operatorname{supp}(\mathbf{i}^*) \mapsto \operatorname{supp}(\mathbf{x}(t))$  such that
  - if  $j \in \operatorname{supp}(\mathbf{i}^*) \cap \operatorname{supp}(\mathbf{x}(t))$ , then  $g_t(j) = j$
  - if  $j \in \operatorname{supp}(\mathbf{i}^*) \setminus \operatorname{supp}(\mathbf{x}(t))$ , then  $(1 + \epsilon) \underbrace{\langle \mathbf{f}_{g_t(j)}, \mathbf{q} \rangle}_{\text{UCB index of arm } g_t(j)} \geq \underbrace{\langle \mathbf{f}_j, \mathbf{q} \rangle}_{\text{UCB index of arm } j}$
- $R(T) = \sum_{k \notin \operatorname{supp}(\mathbf{i}^*)} \sum_{j \in \operatorname{supp}(\mathbf{i}^*) : \Delta_{j,k} > 0} \Delta_{j,k} \sum_{t=1}^T \mathbb{P}[g_t(j) = k]$

- Construct a bijection  $g_t : \text{supp}(i^*) \mapsto \text{supp}(x(t))$  such that
  - if  $j \in \text{supp}(i^*) \cap \text{supp}(x(t))$ , then  $g_t(j) = j$
  - if  $j \in \text{supp}(i^*) \setminus \text{supp}(x(t))$ , then  $(1 + \epsilon) \underbrace{\langle \mathbf{f}_{g_t(j)}, \mathbf{q} \rangle}_{\text{UCB index of arm } g_t(j)} \geq \underbrace{\langle \mathbf{f}_j, \mathbf{q} \rangle}_{\text{UCB index of arm } j}$
- $R(T) \leq \sum_{k \notin \text{supp}(i^*)} \sum_{j \in \text{supp}(i^*) : \Delta_{j,k} > 0} \Delta_{j,k} (l_{j,k} + ll_{j,k})$ , where
 
$$\begin{cases} l_{j,k} = \sum_{t=1}^T \mathbb{P}[g_t(j) = k, N_k(t-1) \leq n_{j,k,\epsilon}] \\ ll_{j,k} = \sum_{t=1}^T \mathbb{P}[g_t(j) = k, N_k(t-1) > n_{j,k,\epsilon}] \end{cases}, \quad n_{j,k,\epsilon} \propto \frac{\log T}{\left(\frac{\mu_j}{1+\epsilon} - \mu_k\right)^2}$$
- Let  $\epsilon = \frac{1}{\log^m T}$ . Then,  $\lim_{T \rightarrow \infty} \frac{R(T)}{\log T} = \mathcal{O}\left(\frac{K-D}{\Delta_{\min}}\right)$ .

- We have developed the first sublinear-time algorithm for matroid semi-bandits.
- Our developed techniques might be use to speedup UCB-style algorithms for other problems, e.g., combinatorial best-arm identification [CLK<sup>+</sup>14, DKC21] and nonstationary semi-bandits [ZWVL20, CWZZ21]
- Another direction is to study the possibility of speeding up other forms of weights, such as those derived from gradients [TWPL23] and those in the follow-the-perturbed-leader algorithm [NB16]

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